

Design and Fabrication of Bubble Barrier with Conveyor

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Abstract—This project emphasis on design and fabrication of the “bubble barrier system” a machine, which involves the removing of waste debris from water, and safely dispose it from the water body. The work was done looking at the current situation of our national rivers, which are dumped by sewage, pollutants, toxic materials, debris etc Bubble barrier generate distinct acoustic and hydrodynamic fields, and through proper manipulation, juvenile carp migration can be prevented. A conveyor will lift the waste surface debris from the water bodies, this will ultimately result in reduction of water pollution and lastly the aquatic animal's death to these problems will be reduced. The main aim of the project is to reduce the man power, time consumption for cleaning the river. In this project we use bubble barrier to clean the flowing water body with help of conveyor we lift the waste from water body

Key words— bubble barrier system, debris, conveyor, water body, etc

1 INTRODUCTION

Water is a basic necessity of humans and all living beings. There is a plenty of water on earth but that is not suitable for human use. Clean water is more important and is used for some purpose. The impurities present in water can cause hazardous diseases.

The Drainage water cleaner system are used to clean wastes from water like polythene, bottles etc. present in water. This can be used to overcome the problem of filtration of wastes from water and it save the time and cost that spend on cleaning the drainage. As the industry setup increase in the environment the water coming from industries are full of wastes like polythene, bottles, and other materials and that water mix with the other water that are used by people and we know that that water is not good for the for health of people. So to overcome from these problems we can filter the water drainage water before it mix with other water. This type of filtration of water is called primary filtration. In this project we use DC or AC motor to run the system when power supply is available & the Equipment we used are motor, chain, driver, bucket, frame, wheel, sprocket gear, solid shaft etc.

we block plastics from moving downstream and make clever use of the current of the river to direct the waste to the banks. We create a bubble barrier by pumping air through a tube with holes, placed on the bottom of the river.

We found an elegant solution that blocks waste in the river, but also allows the passage of fish a barrier of bubbles. By placing two bubble barriers diagonally in the waterway. The upward current that the bubbles generate brings the waste to the surface, and the turbulence stops the waste from flowing downstream. The waste gathers on the side of the river, where it can easily be collected with for example a conveyor belt

2 OBJECTIVES

1. To design and develop Bubble Barrier Conveyor to clean up the plastic soup in water bodies and remove macro plastic form water bodies by conveyor system.
2. Measure and monitor the amount of plastic in the water bodies to help develop better policy and action.
3. To develop the prototype of bubble barrier to conduct experiments
4. Increase the oxygen quantity in water bodies
5. To measure the performance of Bubble Barrier in different water bodies with different bubble size.

3 Methodology and working

Methodology used for whole processing of Machine is given below; this methodology gives way about how work is to be carried out in systematic way. It is standard process of describing process, how it is done in simplest manner in IJSER Transactions are edited electronically.

3.1 Working

The bubble barrier is created by pumping air through a tube with holes which is placed at the bottom of the river. With the help of a compressor device which is located on the bank of the river the compressed air is pumped through tube. The rising bubbles create a barrier of bubbles as these bubbles move up it results in an upwards current which brings the waste to the surface. In order to stop the waste at the surface to flow downstream the tube is placed diagonally on the bottom of river and make clever use of the current of the river to direct the waste to the banks (Figure a). By using this we can remove out the submerged and floating plastic and paper waste from flowing water bodies. By varying the pressure of air flowing through tube, size of the tube and size of the holes we can use this in kinds of water bodies of different depth, flow rate and width. The waste accumulates on the side of the river where it can easily be collected with a catchment system like conveyor system. Fish can pass through the bubbles, underneath the bubble tubing or through the fish pass. Besides the capture of debris, the Bubble Barrier has other positive side effects.

Oxygen levels within the water increase by a Bubble Barrier, which stimulates the ecosystem and stops the growth of toxic blue algae. As bubble screens absorb sounds and waves, fish and shores experience less harm from the ship traffic. By using conveyor waste is screened and carried out of the water body using the mesh buckets to the waste collecting pit. ¼ of the conveyor is submerged in the water where waste is accumulated so that the complete waste is removed out. The conveyor is chain driven and a DC motor is used to drive the conveyor. This motor is made to operate automatically according to the conditions like flow rate and density of waste in river. Automation is done using an electronic system which is fade with programing.

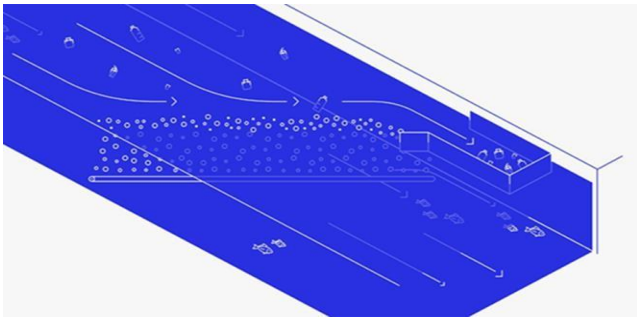


Figure 3.1. Schematic top view of the river, where the Bubble Barrier blocks waste by smart use of the current

3.2 AUTOMATION

Working:- bubble barrier depend on flow of water it works with more efficient in certain flow of water for that taking that as variable if the water flow increase the speed of conveyor should increase and amount of air flow rate should increase .and if the water flow rate is decrease the speed of conveyor should decrease and air flow rate decrease and after the certain water flow rate limit above and below the whole system should shut down

Details :- for this automation arduino is used and for water flow rate water sensor is used and for display of water flow rate and status (efficiency) of system led screen and motor for conveyor and dc power supply all are inter connected to arduino for complete automated.

3.3 Bubble Physical Characteristics

Understanding the formation of a single bubble through an orifice is vital to developing diffusers that can create well defined and predictable physical fields. Bubble formation is driven by

two main components, buoyancy and surface tension. The buoyancy force acts to drive the bubble towards the surface, while the surface tension acts to keep the bubble attached around the orifice. As the bubble size increases, the buoyancy force overcomes the surface tension and the bubble detaches from the surface. Bubble formation creates pressure waves (sound) throughout the liquid and accounts for most of the sound generated by a bubble curtain. As the bubbles rise, they coalesce (merge to form larger bubbles). The thickness of the bubble curtain also increases as the bubbles rise. These characteristics were utilized to design two diffuser types; finebubble and coarse-bubble.

When a bubble is disturbed by a pressure wave, it causes the bubble wall to pulsate or oscillate at a resonant frequency. Theoretical relationships have been developed to predict the resonant frequency and amplitude of the pressure wave created by an oscillating bubble. Understanding the small scale characteristics of bubbles may provide insight to interpreting the sound signal generated by a bubble barrier, and potentially improve the barrier design. The resonant angular frequency, natural frequency of bubble wall oscillations, of a singular bubble is provided by Minneart's frequency

4. Calculation

1) Determine the velocity ratio of the chain drive

$$\text{Velocity ratio} = N1/N2$$

$$\text{So, } N1/N2 = T2/T1, \text{ velocity ratio} = 1$$

2) Select the minimum number of teeth on the smallest sprocket or pinion

$$\text{Minimum Number of Teeth on the Sprocket} = 18$$

3) Determine the design power by using the service factor, such that

$$\text{Design power} = \text{Rated power} \times \text{Service factor (Ks)}$$

$$= 106.25 \times \text{Service factor (Ks)} = 106.25 \times (\text{Load factor (K1)} \times (\text{Lubrication factor (K2)} \times \text{rating factor (K3)})$$

$$= 106.25 \times (1.5 \times 1 \times 1.25)$$

$$\text{Design power} = 0.20\text{kW}$$

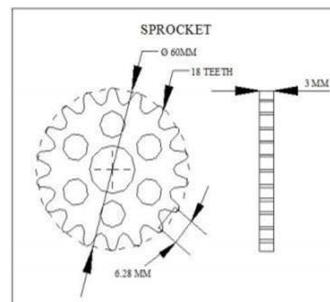


Figure 3.1.sprocket

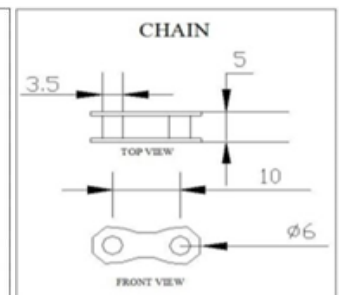


Figure 3.2.chain

4.1Motor calculation:

Type: - DC Motor

$$\text{Power} = V \times I$$

Where, Volt= 12V
Amp=7.6 amp
Power= 12×7.6
Power= 85 watt

4.2 Design of spur gear

Design power
 $P_d = P_r \times K_i$
Where $K_i = 1.25$ for light shocks (8 to 10 hrs a day)
 $P_d = 85 \times 1.25$
 $P_d = 106.25$ watt

4.3 Total load:

Total load $F_t = P_d \div V_p$
Where,
 F_t = tooth load
 V_p = pitch line velocity

4.4 Angular velocity

$V_p = (\pi D_p N) / (60 \times 1000)$
 $V_p = (\pi D_p N) / 60$
Where,
 $D_p = m \times t_p$ t_p = pinion
teeth=24
 $V_p = (\pi \times m \times 24 \times 30) / 60$ $V_p = 0.03769$ m

4.5 Tangential force $F_t = P_d$

$\div V_p$
 $F_t = 106.75 \div 0.03769$ m
 $F_t = 2832 / m$

4.6 Bending strength by Lewis equation, $FB =$

$S_o \times C_v \times b \times y \times m$
Where S_o = Basic strength Mpa
 $S_o = 245$ Mpa SAE 1045 heat treated $C_v = 0.4$ (assume) $b =$ Face width = 10m Modified Lewis factor 20o full depth
 $Y_p = 0.485 - (2.87 / t_p)$ for pinion
 $Y_p = 0.3667$
 $Y_g = 0.485 - (2.87 / t_g)$ for gear
 $Y_g = 0.42583$
 $FB = S_o \times C_v \times b \times y \times m$
 $FB = 245 \times 0.4 \times 10 \times m \times 0.3667 \times m$
 $FB = 359.36 m^2$

Using criteria,

$F_t = FB$
 $2832.31 / m = 359.36 m^2$ $m = 1.99$ mm
 $m = 2$ mm design book table
 $D_p = 48$ mm
 $D_g = 96$ mm
 $FB = S_o \times C_v \times b \times y \times m$ $b = 1993.75 / 245 \times 0.4 \times 0.3255 \times 2$ $b =$
20mm $b = 10 \times m = 20$

Now, checking face width

$F_t = FB$
 $F_t = 2832.31 / m = 1416.15 N$
 $F_t = 1416.15 N$
 $FB = 359.36 m^2$
 $FB = 1438.75 N$
 $F_t < FB$
Design is safe

4.7 Dynamic load:

$F_d = F_t + (21 V_p (C_e b + F_t) / 21 V_p + \sqrt{C_e b + F_t})$
 $V_p = 0.02827 \times m$
 $V_p = 0.075$ m/sec
Where,
 $C =$ Deformation Factor table XVI-4 $C = 11800 - (20 \times \text{full depth})$ $b = 1$
 $e =$ error in profile = 0.05
 $F_d = 1416.15 + (21 \times 0.075 (11800 \times 0.05 \times 20 + 1416) \times 21 \times 0.075 + \sqrt{11800 \times 0.05 \times 20 + 1416})$
 $F_d = 1595$ N
 $F_d > F_t$

4.8 Limiting wear strength

$F_w = D_p \times b \times k \times Q$ $Q =$
 $2 t_g / (t_g + t_p)$
 $= 2 \times 48 / (48 + 24)$
 $Q = 1.33$
 $F_w = 48 \times 20 \times k \times 1.33$
 $F_w = 1276 K$

Using Criteria,

$F_d = F_w$
 $1594 = 1276 K$
 $K = 1.24$
BHN core = 350 For pinion 20o full depth involute profile
 $F_w = 1582$ N
 $F_d > F_w$

4.9 Endurance strength

$F_{en} = S_{eb} \times b \times Y_p \times m$
Where $S_{eb} = 596$ mpa $Y_p = 0.3667$ $b = 20$ $m = 2$
 $F_{en} = 596 \times 20 \times 0.3667 \times 2$
 $F_{en} = 8742$ N $F_{en} > F_d$ Hence design is safe.

5.1.10 Gear ratio:

$N_1 / N_2 = T_2 / T_1$
Where,
 $N_1 =$ rpm of pinion
 $N_2 =$ rpm of gear
 $T_2 =$ teeth of gear
 $T_1 =$ teeth of pinion
 $30 / N_2 = 48 / 24$ $N_2 = 15$ RPM
Power = $2 \pi N T / 60$
Torque $T = 1416 \times 0.048 = 67.96$ N
Power = $2 \times 3.14 \times 15 \times 67.96 / 60$

Density of the water, $\rho = 1000 \text{ kgm}^{-3}$
 The Acceleration of gravity, $g = 9.81 \text{ ms}^{-2}$
 Water pressure $P_1 = P_a + P_h$
 Where,
 P_a = atmospheric pressure
 P_h = hydrostatic pressure
 $(P_h = \rho gh)$
 Pressure at surface is equal to atmospheric pressure
 $P_2 = P_a$
 $P_1 V_1 = P_2 V_2$
 $(P_a + \rho gh) \times \frac{4}{3} \pi r_1^3 = P_a \times \frac{4}{3} \pi r_2^3$
 $r_2 = \left(\frac{(P_a + \rho gh) (r_1)^3}{P_a} \right)^{1/3}$
 Bubble Radius at surface of water is $r_2 = 7 \text{ mm}$

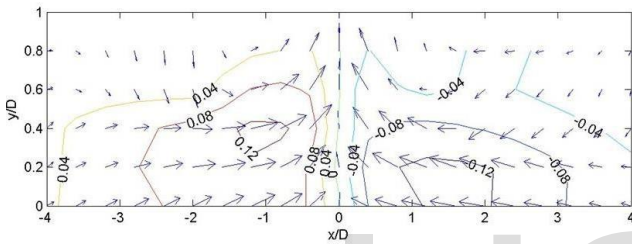


Figure 4.1. Velocity field for coarse-bubble diffuser at 2.5 Ls-1m-1

Table 4.1. Compare b/w fine bubble and coarse bubble

Diffuser Type	Flow-rate (Ls-1m-1)	Depth (cm)	Maximum Velocity (cm/s)	Stagnation Point Location (X,Y)
Fine-Bubble	1	25	8	(+/-1,0.6)
	2.5	25	16	(+/-1,0.75)
	2.8	25	17	(+/-0.8,0.6)
	2.5	50	13	(+/-1.5,0.75)
	2.8	50	16	(+/-2,0.75)
Coarse-Bubble	2.5	25	12	(+/-1,>0.8)
	2.8	25	13	(+/-1.5,>0.8)

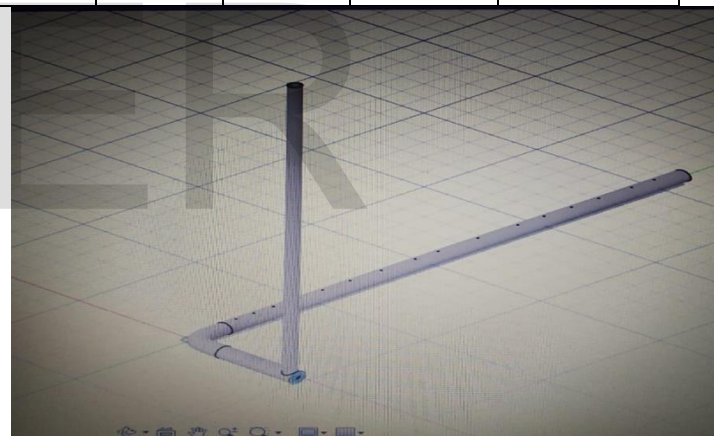
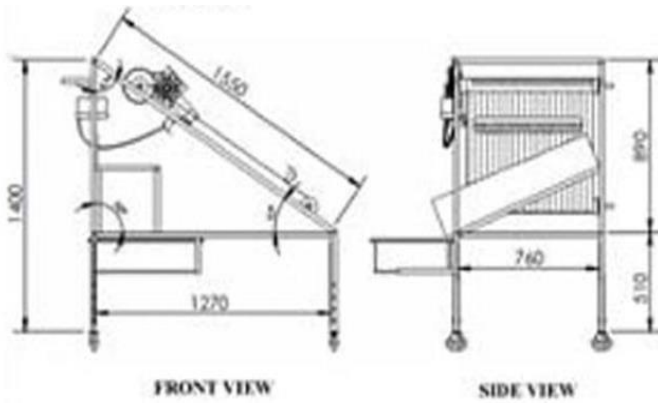


Figure 5.1. design of diffuser

5. Design and Analysis



Parameters (conveyor)	specifications
1. Height (with stand)	1400mm
2. length	1200mm
3. Width	700mm
4. Inclined length	1040mm
5. Inclined angle	36 degree
6. Height (without stand)	890mm

Parameters(bubble barrier)	specifications
Length	2500mm
Height	600mm
Width	500mm
Pipe diameter	35mm
Hole diameter	Varies depends requirement bubbles
Air compressor(pressure)	300psi

6. RESULTS AND DISCUSSIONS

The Bubble Barrier will reduce the amount of plastic pollution in rivers and can help raising awareness in order to prevent further plastic pollution and it can be placed in various rivers and canals.

1. It catches more plastic than current solutions in flowing water because we can reach plastic (> 1mm) in the total width and depth of a river. A Bubble Barrier can be placed both in rivers as in small canals.
2. By the theoretical analysis and calculation we can get more efficiency with varying the size of the hole diameter.
3. The waste debris which are collected in bubble barrier that will be simultaneously dumped out of the canal by automatic operated conveyor. And speed of the conveyor belt is regulated with respect to the diffuser variation

7. CONCLUSION

Hence we can conclude that the main objective of this project “design and fabrication of bubble barrier with conveyor” is used for various purposes like,

1. The rising bubbles result in an upward current, which brings plastic waste to the surface. Water flow directs it to the side of the water body stopping it from flowing further downstream
2. We can measure and monitor the amount of plastic in the water bodies by varying with help of diffuser.

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